

Are Bayesian networks always suitable?

- Problem (modelling) objective, e.g., for function approximation or pure numeric prediction without a need to explain the results a “black box” model such as neural networks can be sufficient
- Sufficient knowledge about the problem (domain experts, data)
- Complexity of the problem e.g., is it decomposable

Building Bayesian Networks

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Problem solving

Bayesian networks: a **declarative** knowledge-representation formalism, i.e.,:

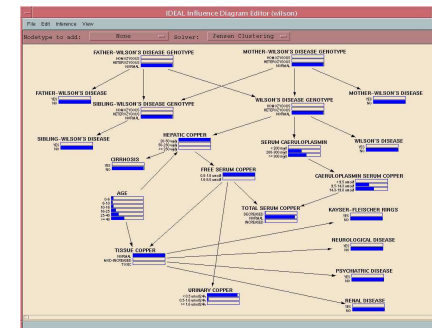
- mathematical basis
- problem to be solved determined by (1) entered evidence \mathcal{E} (including potential decisions); (2) given hypothesis $H : P(H | \mathcal{E})$

Examples:

- Description of population
- Classification and diagnosis: $D = \arg \max_H P(H | \mathcal{E})$ i.e. D is the hypothesis with maximum $P(H | \mathcal{E})$
- Prediction
- Decision making based on *what-if* scenario's

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Prior information

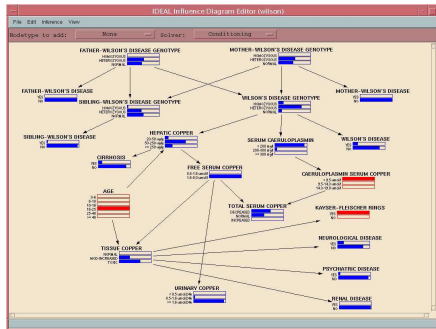


- Marginal probabilities $P(V)$ for every vertex V , e.g., $P(\text{WILSON'S DISEASE} = \text{yes})$
- Gives description of the population on which the assessed probabilities are based

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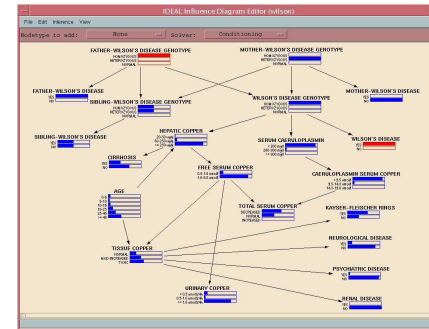
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Diagnostic problem solving



- Marginal probabilities $P^*(V) = P(V | \mathcal{E})$ for every vertex V , e.g., $P(\text{WILSON'S DISEASE} = \text{yes} | \mathcal{E})$ for entered evidence \mathcal{E} (red vertices, with probability for one value equal to 1)
- Gives description of the *subpopulation* of the original population or individual cases

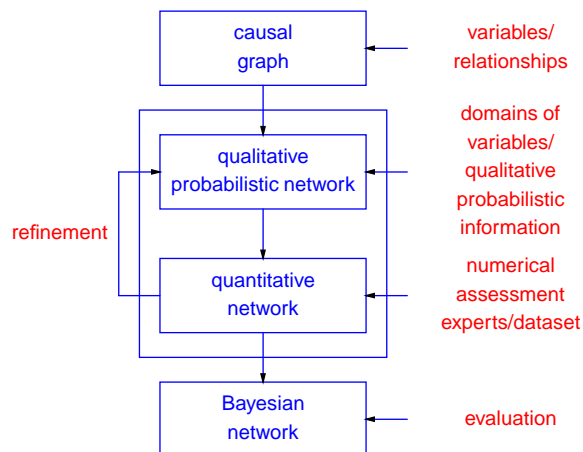
Prediction of associated findings



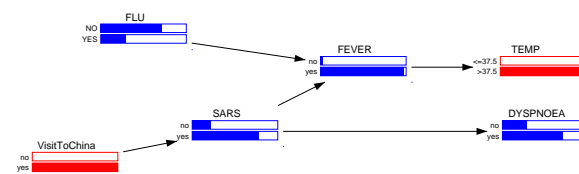
- Marginal probabilities $P^*(V) = P(V | \mathcal{E})$ for every vertex V , e.g., $P(\text{Kayer-Fleischer Rings} = \text{yes} | \mathcal{E})$ with \mathcal{E} evidence
- Gives description of the findings associated with a given class or category, such as Wilson's disease

Design of Bayesian network

- Current design principle: start modelling qualitatively (different from traditional knowledge-based systems)

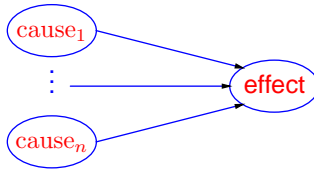


Terminology



- **Parent** SARS of **Child** FEVER
- SARS is **Ancessor** of TEMP
- DYSPNOEA is **Descendant** of VisitToChina
- **Query node**, e.g., FEVER
- **Evidence**, e.g., VisitToChina and TEMP
- **Markov blanket**, e.g., for SARS: {VisitToChina, DYSPNOEA, FEVER, FLU}

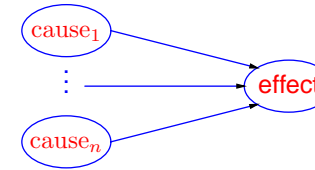
Causal graph: Topology (structure)



- Identify factors that are relevant
- Determine how those factors are causally related to each other
- The arc $\text{cause} \rightarrow \text{effect}$ does mean that cause is a factor involved in causing effect

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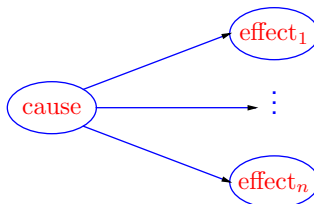
Causal graph: Common effects



- An effect that has two or more ingoing arcs from other vertices is a **common effect** of those causes
- Kinds of causal interaction
 - **Synergy**: POLUTION \rightarrow CANCER \leftarrow SMOKING
 - **Prevention**: VACCINE \rightarrow DEATH \leftarrow SMALLPOX
 - **XOR**: ALKALI \rightarrow DEATH \leftarrow ACID

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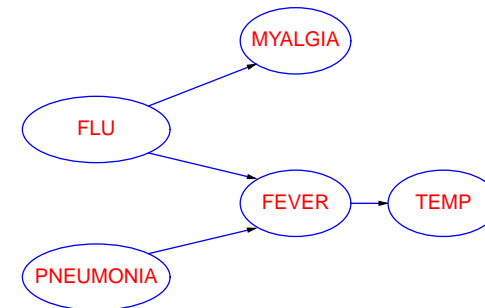
Causal graph: Common causes



- A cause that has two or more outgoing arcs to other vertices is a **common cause (factor)** of those effects
- The effects of a common cause are usually observables (e.g. manifestations of failure of a device or symptoms in a disease)

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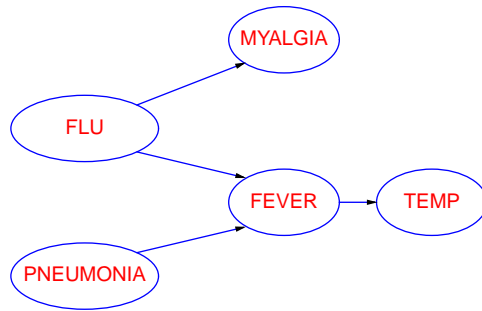
Causal graph: Example



- FEVER and PNEUMONIA are two alternative causes of fever (but may enhance each other)
- FLU has two common effects: MYALGIA and FEVER
- High body TEMPerature is an **indirect effect** of FLU and PNEUMONIA, caused by FEVER

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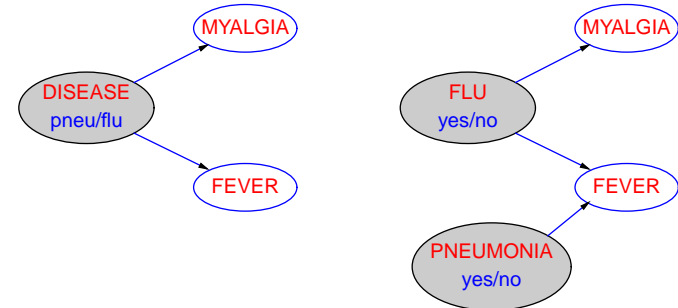
Check independence relationship



- **Conditional independence:** $X \perp\!\!\!\perp Y \mid Z$
 - $\{FLU\} \perp\!\!\!\perp \{TEMP\} \mid \{FEVER\}$
 - $\{FEVER\} \perp\!\!\!\perp \{MYALGIA\} \mid \{FLU\}$
 - $\{PNEUMONIA\} \perp\!\!\!\perp \{FLU\} \mid \emptyset$
 - $\{PNEUMONIA\} \not\perp\!\!\!\perp \{FLU\} \mid \{FEVER\}$

Choose variables

- Factors are **mutually exclusive** (cannot occur together with absolute certainty): put as values in the same variable, or
- Factors may co-occur: multiple variables



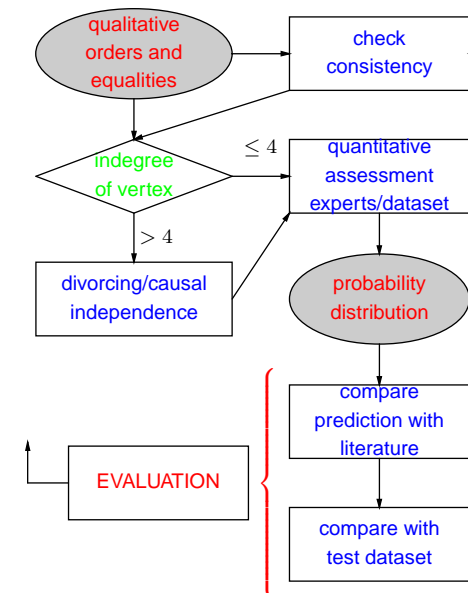
(a) Single variable

(b) Multiple variables

Choose values

- Discrete values
 - Mutually exclusive and exhaustive
 - Types:
 - binary, e.g., FLU = *yes/no*, *true/false*, *0/1*
 - ordinal, e.g., INCOME = *low, medium, high*
 - nominal, e.g., COLOR = *brown, green, red*
 - integral, e.g., AGE = $\{1, \dots, 120\}$
- Continuous values
- Discretization (of continuous and integral values)
 - Example for TEMP:
 - $[-50, +5) \rightarrow$ *cold*
 - $[+5, +20) \rightarrow$ *mild*
 - $[+20, +50] \rightarrow$ *hot*

Probability assessment



Expert judgements

- **Qualitative probabilities:**

- **Qualitative orders:**

AGE	$P(\text{General Health Status} \text{AGE})$
10-69	good > average > poor
70-79	average > good > poor
80-89	average > poor > good
≥ 90	poor > average > good

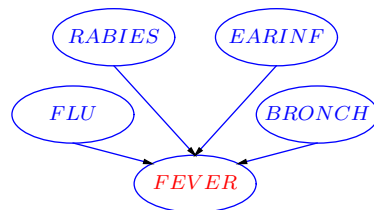
- **Equalities:**

$$P(\text{CANCER} = T1 | \text{AGE} = 15 - 29) =$$

$$P(\text{CANCER} = T2 | \text{AGE} = 15 - 29)$$

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A bottleneck in Bayesian networks



- The number of parameters for the effect given n causes grows exponentially: $\geq 2^n$ (for binary causes)

- **Unlikely evidence combination:**

$$P(\text{fever} | \text{flu}, \text{rabies}, \text{ear_infection}) = ?$$

Problem: for many BNs **too many** probabilities have to be assessed

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Expert judgements (cont.)

- **Quantitative, subjective probabilities:**

	$P(\text{GHS} \text{AGE})$		
AGE	good	average	poor
10-69	0.99	0.008	0.002
70-79	0.3	0.5	0.2
80-89	0.1	0.5	0.4
≥ 90	0.1	0.3	0.6

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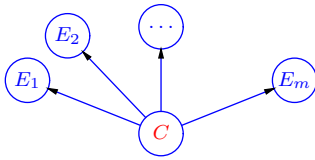
Special form Bayesian networks

Solution: use simpler probabilistic model, such that either

- the **structure becomes simpler**, e.g.,
 - *naive* (independent) form BN
 - *Tree-Augmented Bayesian Network (TAN)*
- or,
- the **assessment of the conditional probabilities becomes simpler** (even though the structure is still complex), e.g.,
 - *parent divorcing*
 - *causal independence BN*

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Independent (Naive) form BN



- C is a **class variable**
- E_i are **evidence variables** and $\mathcal{E} \subseteq \{E_1, \dots, E_m\}$. We have $E_i \perp\!\!\!\perp E_j \mid C$, for $i \neq j$. Hence, using Bayes' rule:

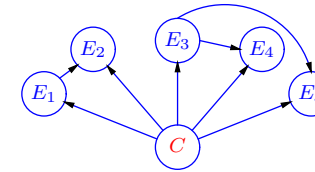
$$P(C \mid \mathcal{E}) = \frac{P(\mathcal{E} \mid C)P(C)}{P(\mathcal{E})} \quad \text{with:}$$

$$P(\mathcal{E} \mid C) = \prod_{E \in \mathcal{E}} P(E \mid C) \quad \text{by cond. ind.}$$

$$P(\mathcal{E}) = \sum_C P(\mathcal{E} \mid C)P(C) \quad \text{marg. \& cond.}$$

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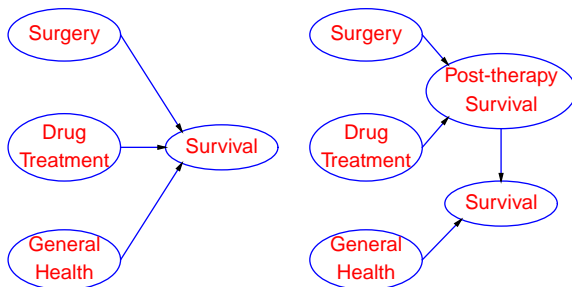
Tree-Augmented BN (TAN)



- Extension of Naive Bayes: reduce the number of independent assumptions
- Each node has at most two parents (one is the class node)

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Divorcing multiple parents



(a) Original network

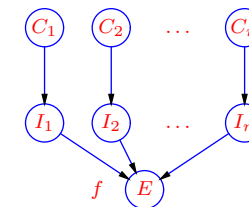
(b) Divorced network

Reduction in number of probabilities to assess:

- Identify a potential common effect of two or more parent vertices of a vertex
- Introduce a new variable into the network, representing the common effect

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Causal Independence



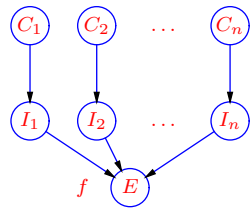
with:

- **cause** variables C_j , **intermediate** variables I_j , and the **effect** variable E
- $P(E \mid I_1, \dots, I_n) \in \{0, 1\}$
- **interaction function** f , defined such that

$$f(I_1, \dots, I_n) = \begin{cases} e & \text{if } P(e \mid I_1, \dots, I_n) = 1 \\ \neg e & \text{if } P(e \mid I_1, \dots, I_n) = 0 \end{cases}$$

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Causal Independence: BN



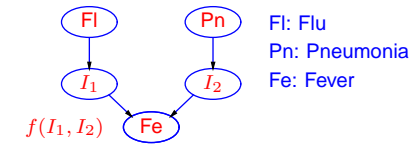
$$\begin{aligned}
 P(e | C_1, \dots, C_n) &= \sum_{I_1, \dots, I_n} P(e | I_1, \dots, I_n) P(I_1, \dots, I_n | C_1, \dots, C_n) \\
 &= \sum_{f(I_1, \dots, I_n) = e} P(e | I_1, \dots, I_n) P(I_1, \dots, I_n | C_1, \dots, C_n)
 \end{aligned}$$

Note that as $I_i \perp\!\!\!\perp I_j | \emptyset$, and $I_i \perp\!\!\!\perp C_j | C_i$, for $i \neq j$, it holds that:

$$P(I_1, \dots, I_n | C_1, \dots, C_n) = \prod_{k=1}^n P(I_k | C_k)$$

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Example of causal independence



$$\begin{aligned}
 P(fe | Fl, Pn) &= \sum_{I_1, I_2} P(fe, I_1, I_2 | Fl, Pn) \sum_{I_1, I_2} P(fe | I_1, I_2, Fl, Pn) P(I_1, I_2 | Fl, Pn) \\
 &= \sum_{I_1, I_2} P(fe | I_1, I_2) P(I_1 | Fl) P(I_2 | Pn)
 \end{aligned}$$

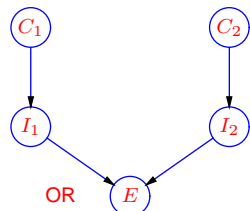
Select **only** those $P(I_1 | Fl) P(I_2 | Pn)$ for which $f(I_1, I_2) = fe$, i.e. $P(fe | I_1, I_2) = 1$; do not select if $f(I_1, I_2) = \neg fe$, i.e. $P(fe | I_1, I_2) = 0$

Result:

$$P(fe | Fl, Pn) = \sum_{f(I_1, I_2) = fe} P(I_1 | Fl) P(I_2 | Pn)$$

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Causal independence: Noisy OR

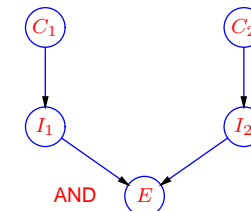


- Interactions among causes, as represented by the function f and $P(E | I_1, I_2)$, is a logical OR
- Meaning: presence of any one of the causes C_i with absolute certainty will cause the effect e (i.e. $E = true$)

$$\begin{aligned}
 P(e | C_1, C_2) &= \sum_{I_1 \vee I_2 = e} P(e | I_1, I_2) \prod_{k=1,2} P(I_k | C_k) \\
 &= P(i_1 | C_1) P(i_2 | C_2) + P(\neg i_1 | C_1) P(i_2 | C_2) \\
 &\quad + P(i_1 | C_1) P(\neg i_2 | C_2)
 \end{aligned}$$

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Causal independence: Noisy AND



- Interactions among causes, as represented by the function f and $P(E | I_1, I_2)$, is a logical AND
- Meaning: presence of all causes C_i with absolute certainty will cause the effect e (i.e. $E = true$); otherwise, $\neg e$

$$\begin{aligned}
 P(e | C_1, C_2) &= \sum_{I_1 \wedge I_2 = e} P(e | I_1, I_2) \prod_{k=1,2} P(I_k | C_k) \\
 &= P(i_1 | C_1) P(i_2 | C_2)
 \end{aligned}$$

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Refining causal graphs

“Essentially, all models are wrong but some are useful”

G.Box, N.Draper (1987)

So, model refinement is necessary.

● **How:**

- Manual
- Automatic

● **What:**

- Probability adjustment
- Removing irrelevant factors
- Adding previously hidden, unknown factors
- Causal relationships adjustment, e.g., including, removing independence relations