

The EfProb Library for Probabilistic Calculations

<https://efprob.cs.ru.nl/>

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CALCO Tools
15 June 2017

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➡ EfProb: a **Python** library for discrete/continuous/quantum probability calculations

Talk plan

- ① Language: States, Predicates, and Channels
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A **state** on a set X is a **distribution** $\sigma \in \mathcal{D}(X)$, i.e. $\sigma: X \rightarrow [0, 1]$ with $\sum_x \sigma(x) = 1$. Often denoted as a formal convex sum, e.g. $\frac{1}{3}|a\rangle + \frac{1}{2}|b\rangle + \frac{1}{6}|c\rangle$, for $a, b, c \in X$

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Operations for states $\sigma \in \mathcal{D}(X)$, $\tau \in \mathcal{D}(Y)$, $\omega \in \mathcal{D}(X \times Y)$

- **Joint state** $\sigma \otimes \tau \in \mathcal{D}(X \times Y)$ by $(\sigma \otimes \tau)(x, y) = \sigma(x) \cdot \tau(y)$
- **Marginal state** $\omega_1 \in \mathcal{D}(X)$ by $\omega_1(x) = \sum_y \omega(x, y)$

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- **Truth** $\mathbf{1}_X$, **falsity** $\mathbf{0}_X$, and **negation** $(\sim p)(x) = 1 - p(x)$
- **Sequential conjunction** $p \& q$ by $(p \& q)(x) = p(x) \cdot q(x)$

Discrete prob., validity & conditioning

For a state $\sigma \in \mathcal{D}(X)$ and a predicate $p \in [0, 1]^X$,
the **validity**

$$\sigma \models p \quad := \quad \sum_x \sigma(x) \cdot p(x) \in [0, 1]$$

- *Probability that p holds in σ*

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When the validity $\sigma \models p$ is non-zero,
the **conditional state** $\sigma/p \in \mathcal{D}(X)$ (' σ given p ') defined by

$$(\sigma/p)(x) := \frac{\sigma(x) \cdot p(x)}{\sigma \models p}$$

- *Updated state after we observe that p holds*

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Comparing to traditional notation, for events $A, B \subseteq X$

- $P(A) = \sigma \models \mathbf{1}_A$
- $P(A | B) = \sigma/\mathbf{1}_B \models \mathbf{1}_A$

Discrete probability, channels

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State/predicate transformation by a channel $c: X \rightarrow Y$

For a state $\sigma \in \mathcal{D}(X)$,

$$\text{state } c \gg \sigma \in \mathcal{D}(Y) \quad \text{by} \quad (c \gg \sigma)(y) = \sum_x c(x, y) \cdot \sigma(x)$$

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For a predicate $q \in [0, 1]^Y$, $\text{Pred}(X) \xleftarrow{c \ll} \text{Pred}(Y)$

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Forward and **backward learning** are described as
 $c \gg (\sigma/p)$ and $\sigma/(c \ll q)$ [Jacobs & Zanasi, MFPS 2016]

Uniform language: continuous / quantum

For **continuous probability**:

States are probability density functions $\sigma: X \rightarrow \mathbb{R}_{\geq 0}$ such that $\int \sigma(x) dx = 1$ (where $X \subseteq \mathbb{R}^n$)

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States are positive trace-one matrices

Predicates are positive matrices with eigenvalues ≤ 1

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- Operations $\sigma \models p$ etc. exist in quantum theory.

Note: $p \& q \neq q \& p$

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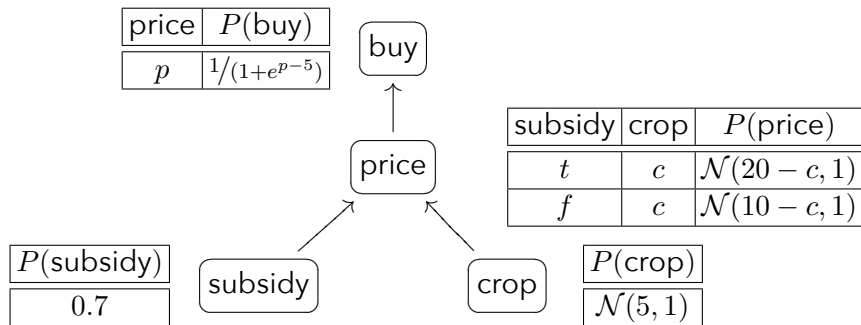
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- Works well for moderate-size problems; but not meant for large-scale computation
- Can be helpful eg. for research and teaching

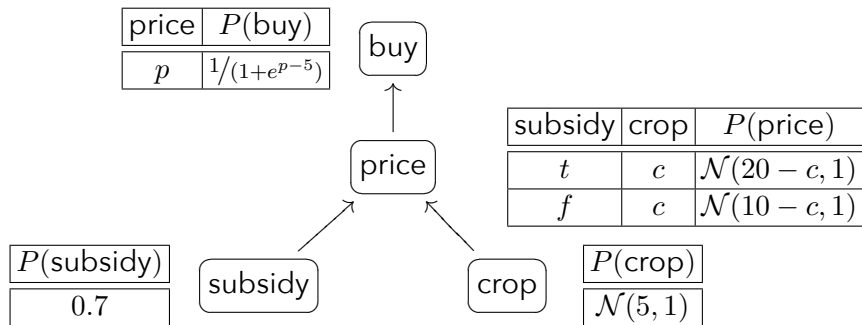
Demo: Hybrid Bayesian Network example

From [Cobb & Shenoy, 2006]



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- 'subsidy' and 'buy' have **discrete** domain $\{t, f\}$
- 'crop' and 'price' have **continuous** domain \mathbb{R}
- $\mathcal{N}(\mu, \sigma)$ normal (Gaussian) distribution

Conclusions

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